

# How accurate is my air quality monitor?

21st April 2024, Dr. Anika Krause





**Concepts of accuracy and precision**

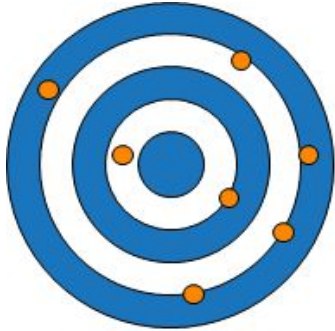
**Experiments to determine sensor performance**

**How to quantify accuracy & precision**

**What's an acceptable error?**

**Examples**

# Precision versus accuracy



Low accuracy  
Low precision



Low accuracy  
High precision



High accuracy  
Low precision

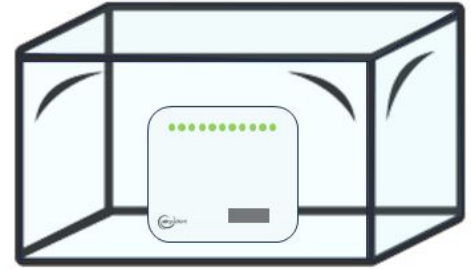


High accuracy  
High precision

**Precision** refers to the consistency and repeatability of measurements, regardless of how far these are from the true value.

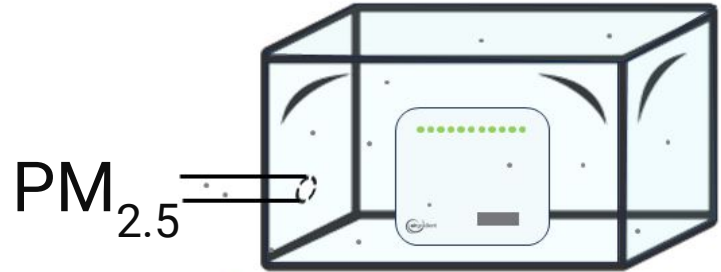
**Accuracy**, on the other hand, refers to how close a measurement is to the true or target value, regardless of whether it's consistently reproducible.

# Precision versus accuracy of air quality sensors



*Place sensor in an airtight box*

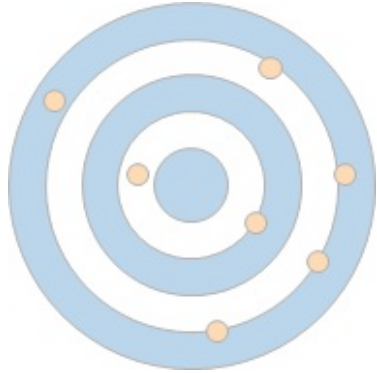
# Precision versus accuracy of air quality sensors



Concentration =  $20 \mu\text{g}/\text{m}^3$

*Fill box with a known pollution concentration.*

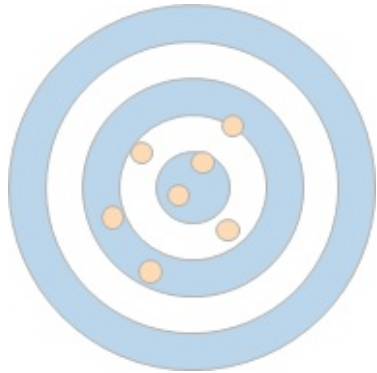
# Precision versus accuracy of air quality sensors



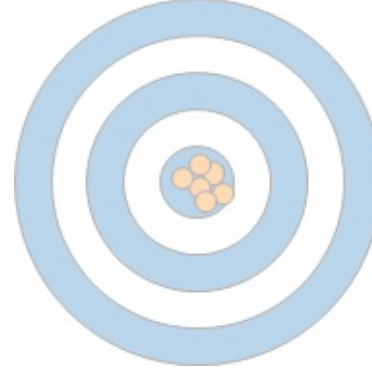
Low accuracy, low precision



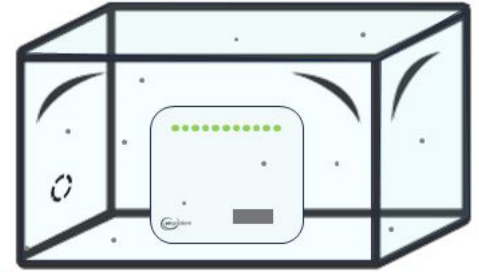
Low accuracy, high precision



High accuracy, low precision

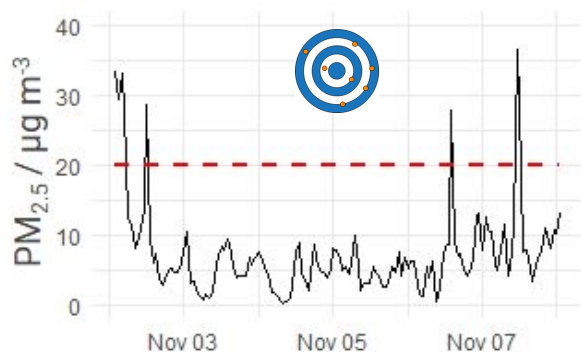


High accuracy, high precision

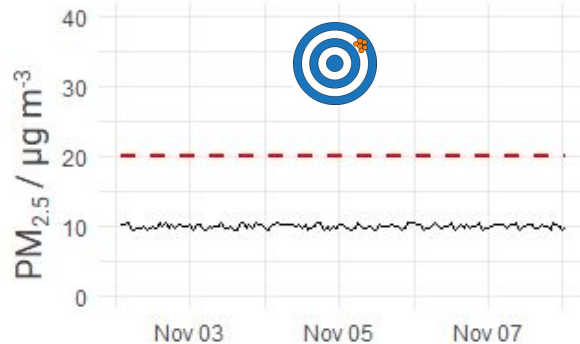


Concentration =  $20 \mu\text{g}/\text{m}^3$

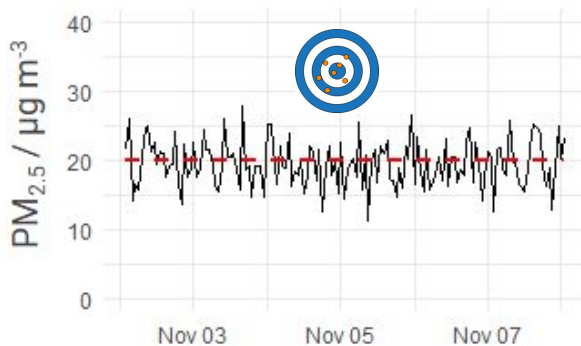
# Precision versus accuracy of air quality sensors



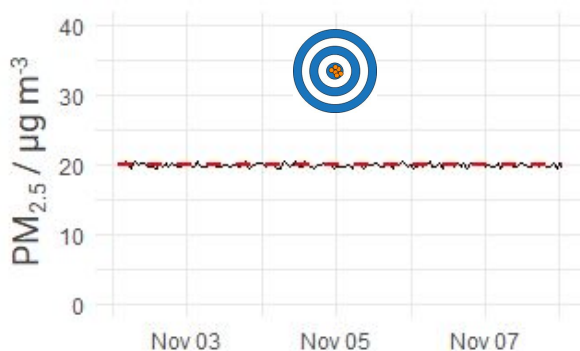
**Low accuracy, low precision**



**Low accuracy, high precision**



**High accuracy, low precision**

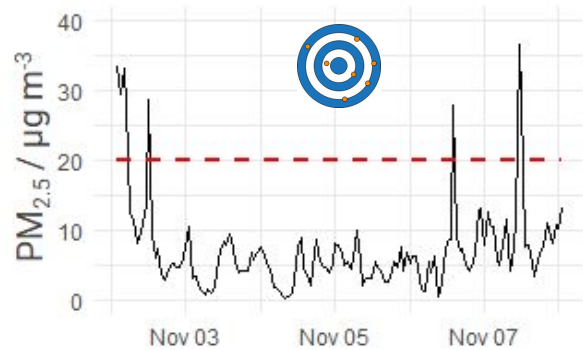


**High accuracy, high precision**

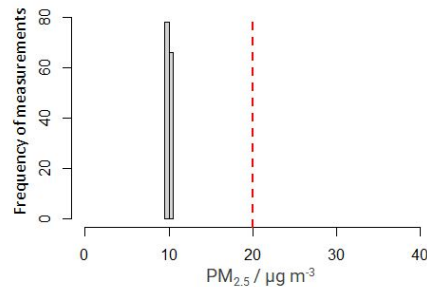


Concentration = 20  $\mu\text{g/m}^3$

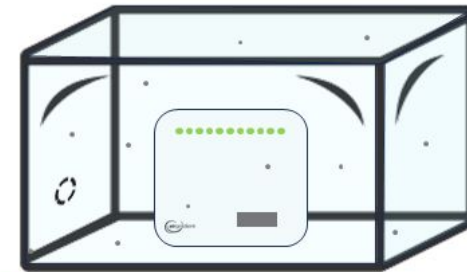
# Precision versus accuracy of air quality sensors



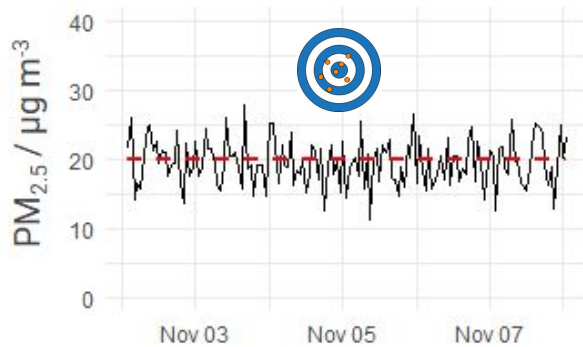
Low accuracy, low precision



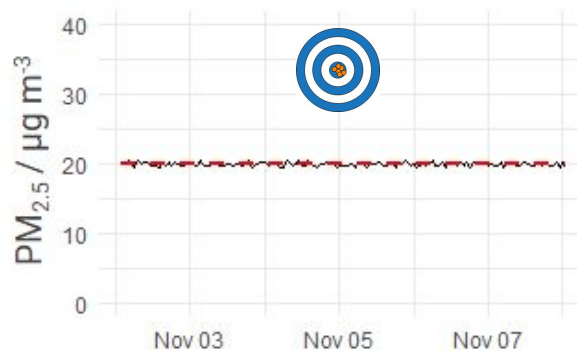
Low accuracy, high precision



Concentration = 20  $\mu\text{g/m}^3$



High accuracy, low precision



High accuracy, high precision

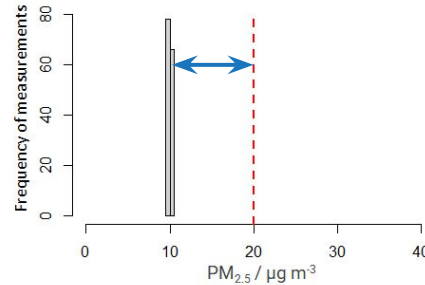


# Precision versus accuracy of air quality sensors

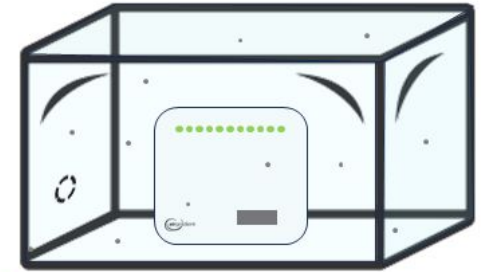
## Accuracy

(Average) difference between measurement and true value.

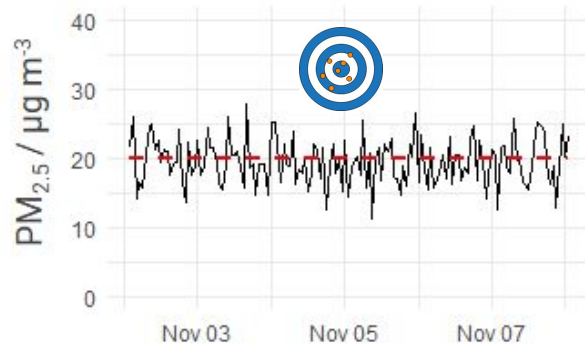
The smaller the difference (=error), the higher the accuracy.



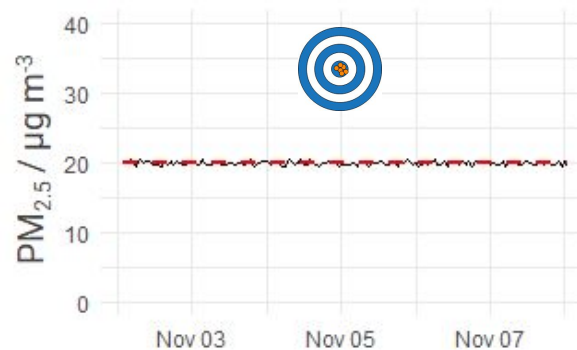
Low accuracy, high precision



Concentration = 20 μg/m<sup>3</sup>



High accuracy, low precision



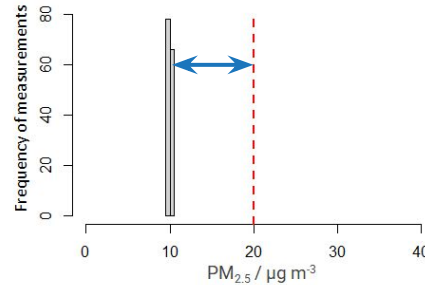
High accuracy, high precision

# Precision versus accuracy of air quality sensors

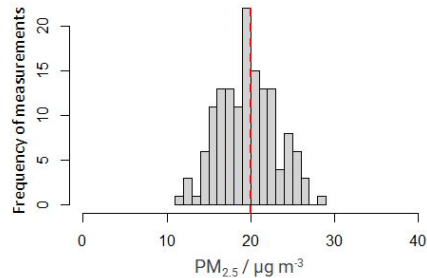
## Accuracy

(Average) difference between measurement and true value.

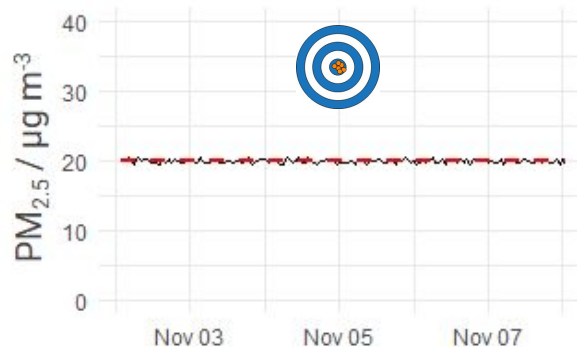
The smaller the difference (=error), the higher the accuracy.



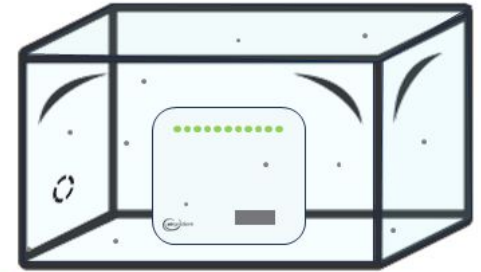
Low accuracy, high precision



High accuracy, low precision



High accuracy, high precision



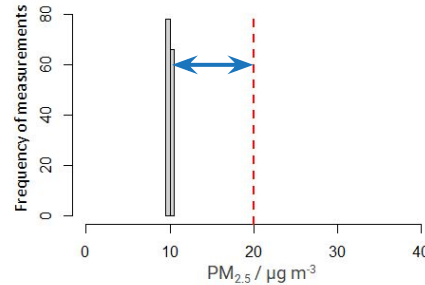
Concentration = 20 µg/m<sup>3</sup>

# Precision versus accuracy of air quality sensors

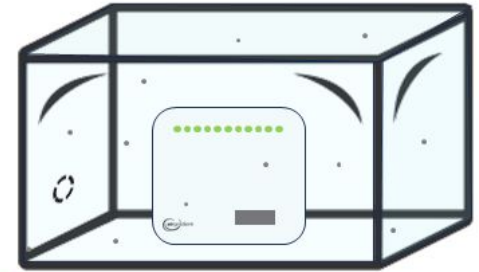
## Accuracy

(Average) difference between measurement and true value.

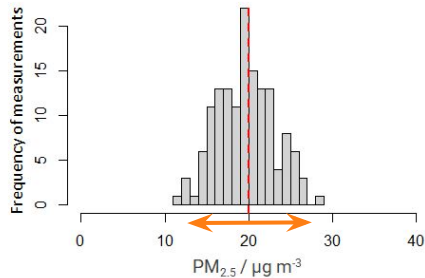
The smaller the difference (=error), the higher the accuracy.



Low accuracy, high precision



Concentration = 20 µg/m<sup>3</sup>

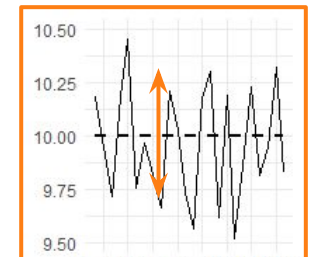


High accuracy, low precision

## Precision

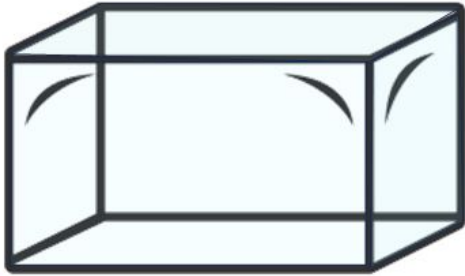
(Average) distance of the measurements from the average value.

The narrower the distribution, the higher the precision.



# Practical considerations

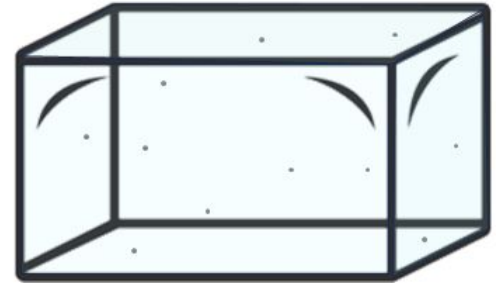
Clean air



Known number of particles

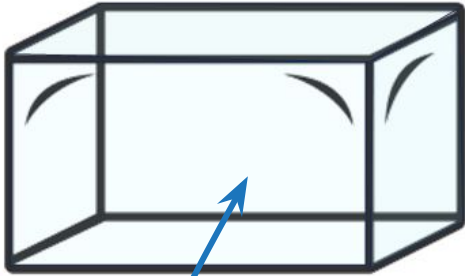


Stable and known PM concentration



# Practical considerations

Clean air



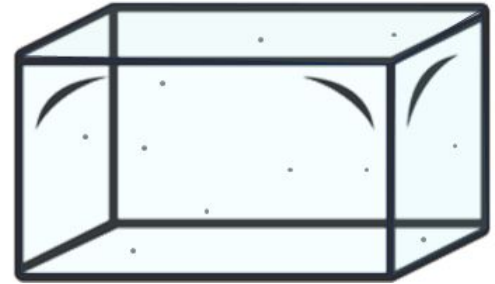
*How to pre-clean the air?  
- it's complicated...*

Known number of  
particles



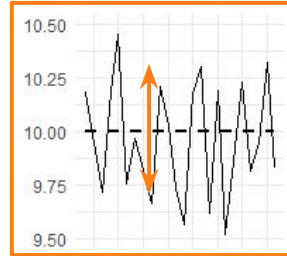
*Where can I buy this?  
- even more complicated...*

~~Stable and known~~  
PM concentration

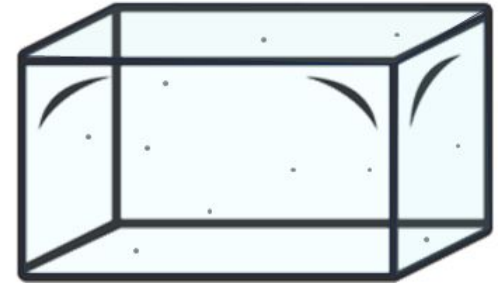


Could still measure precision?

For this, the concentration just needs to be stable



~~Stable and known~~  
PM concentration

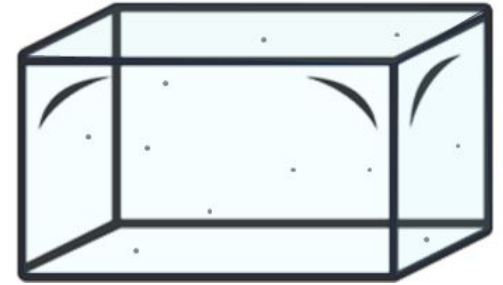


# Practical considerations



*Advantage of low-cost sensors: You can have many!*

~~Stable and known~~  
PM concentration



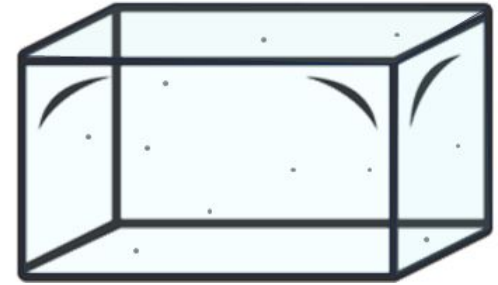
*Space?*

# Practical considerations



*Advantage of low-cost sensors: You can have many!*

~~Stable and known~~  
PM concentration

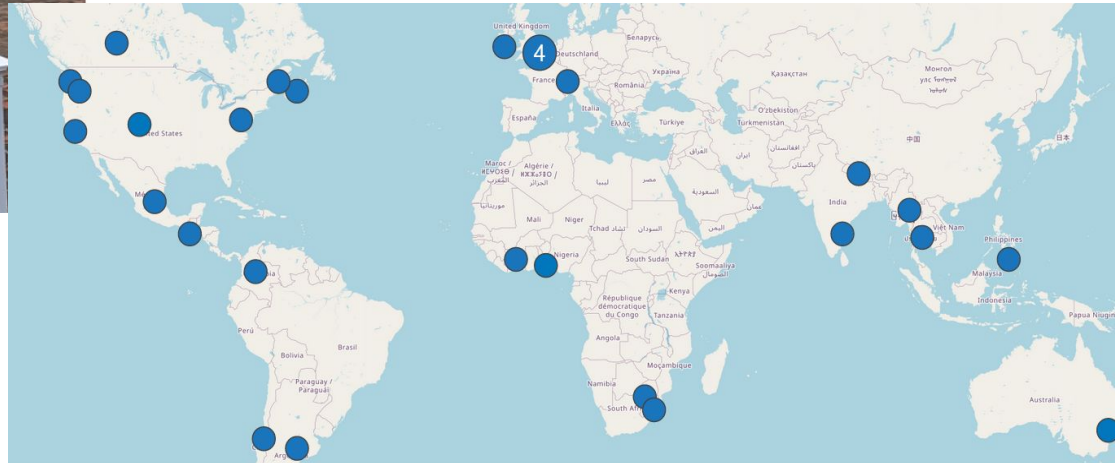


*Space?*

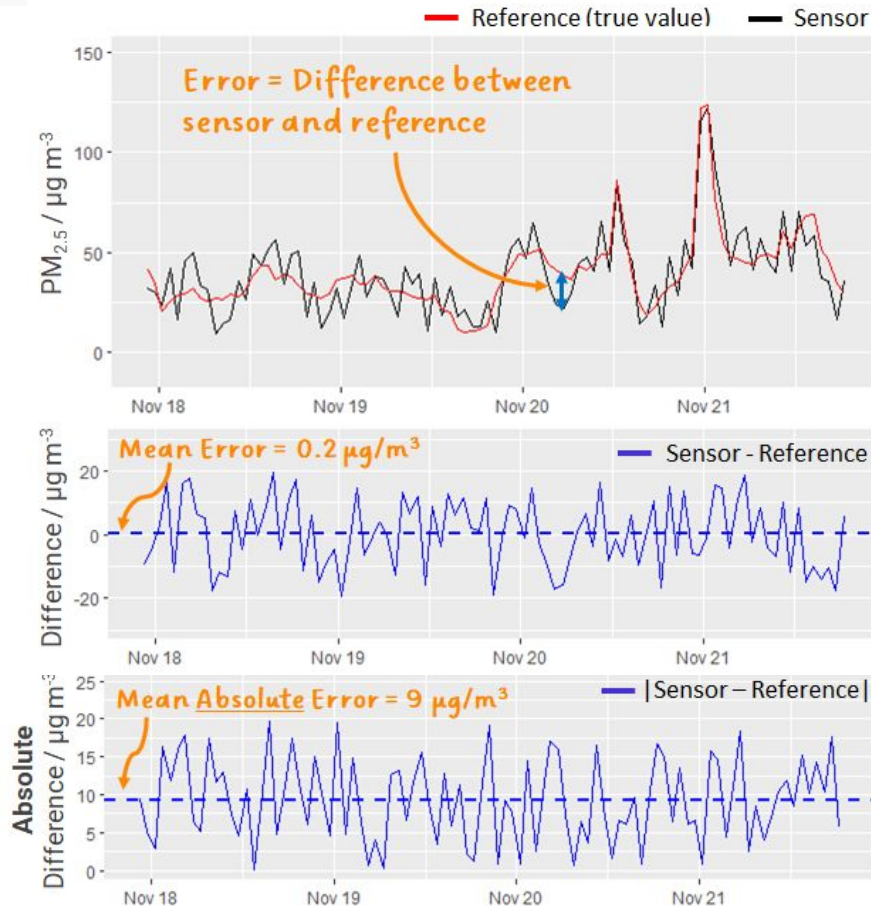
**Chamber testing is not practicable.**



# Co-location with reference



# How to measure the accuracy of a sensor?



Difference

Average  
(=mean) error

Mean absolute error (MAE)



**Accuracy**

(Average) difference between measurement and true value.

## Mean Absolute Error

How far off are the sensors from the reference data i.e. Error

Adding the errors up over all readings from the testing period

Absolute value so everything is positive

$$\text{MAE} = \frac{\sum_n |c_{\text{sens},n} - c_{\text{ref},n}|}{n}$$

To get the mean you divide by the number of readings

The diagram illustrates the Mean Absolute Error (MAE) formula. The formula is  $\text{MAE} = \frac{\sum_n |c_{\text{sens},n} - c_{\text{ref},n}|}{n}$ . Handwritten blue annotations explain each part: 'How far off are the sensors from the reference data i.e. Error' points to the absolute value term; 'Adding the errors up over all readings from the testing period' points to the summation symbol; 'Absolute value so everything is positive' points to the absolute value bars; and 'To get the mean you divide by the number of readings' points to the denominator  $n$ .

## Alternative parameter: Root Mean Square Error

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_n (c_{\text{sens},n} - c_{\text{ref},n})^2}$$

(R) square Root to compensate for the squaring

(S) Squaring makes everything positive and increases sensitivity

(M) to get the Mean you divide by the number of readings

(E) difference between sensors and reference i.e. the Error

Adding the squared errors up over all the readings from the testing period

- Measure of the average error of a sensor (like MAE)
- Always higher or equal to MAE → stricter criterion
- Recommended by US EPA

## Good Sensor vs. Bad Sensor



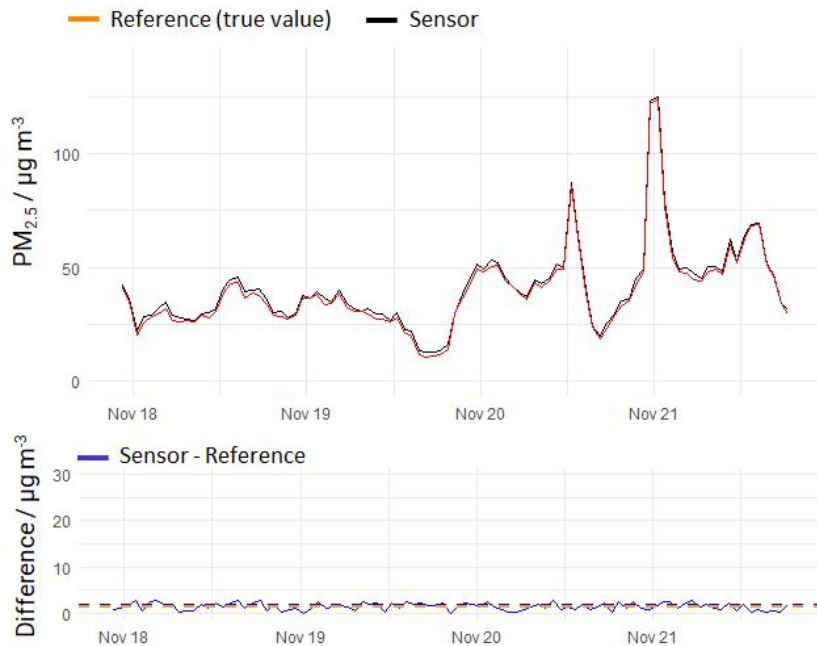
From: The Lego Movie / <https://hero.fandom.com>

## Clean vs. Polluted



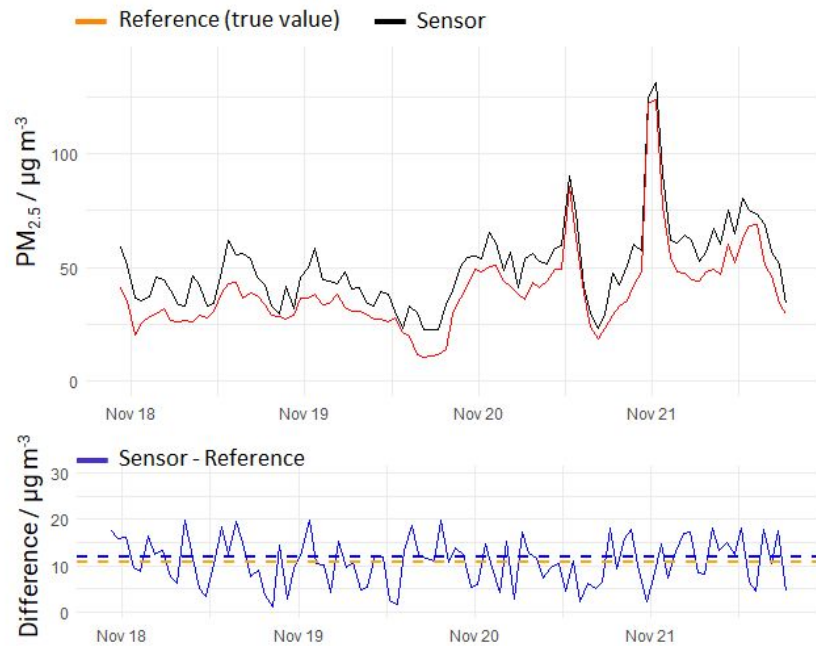
# Example I: Good sensor vs. bad sensor

## Good sensor



MAE = 1.5  $\mu\text{g/m}^3$  RMSE = 1.7  $\mu\text{g/m}^3$

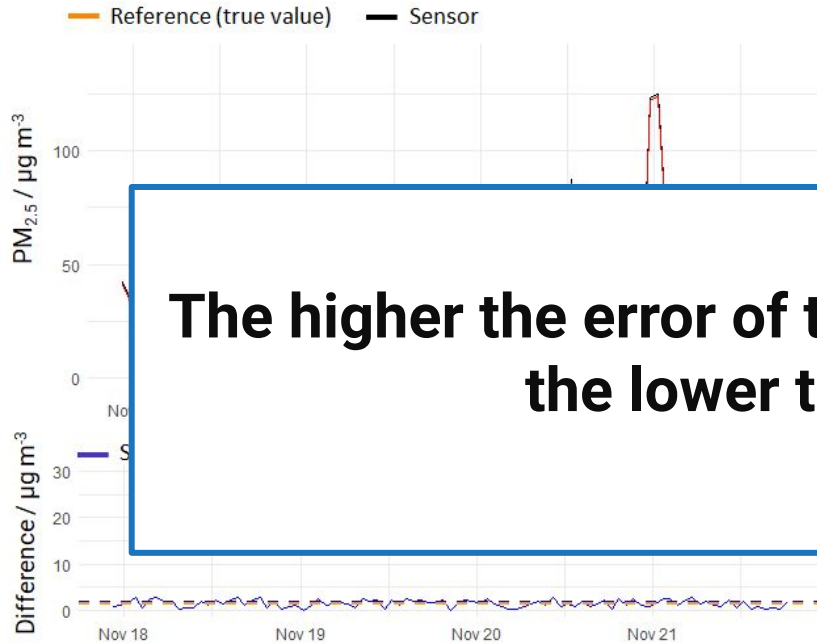
## Bad sensor



MAE = 10.4  $\mu\text{g/m}^3$  RMSE = 12.0  $\mu\text{g/m}^3$

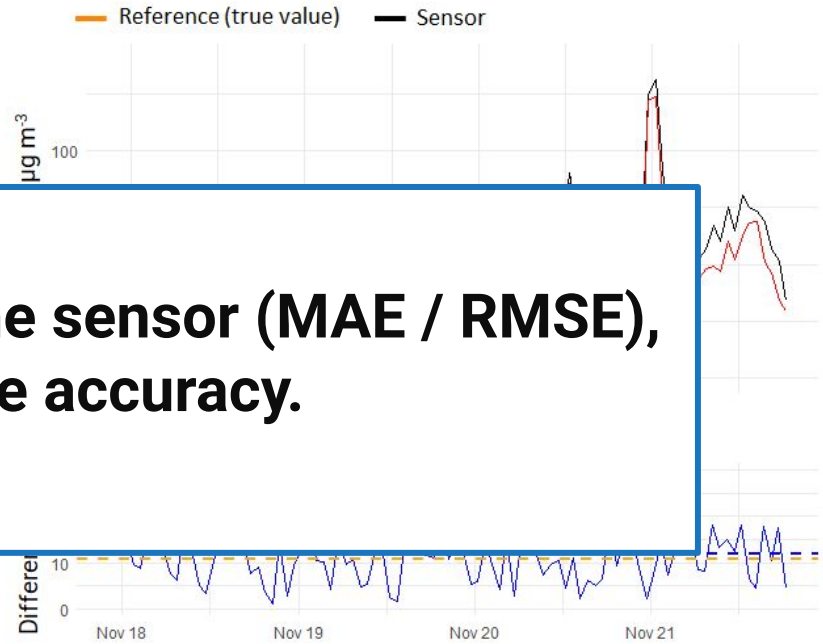
# Example I: Good sensor vs. bad sensor

## Good sensor



MAE = 1.5  $\mu\text{g/m}^3$  RMSE = 1.7  $\mu\text{g/m}^3$

## Bad sensor

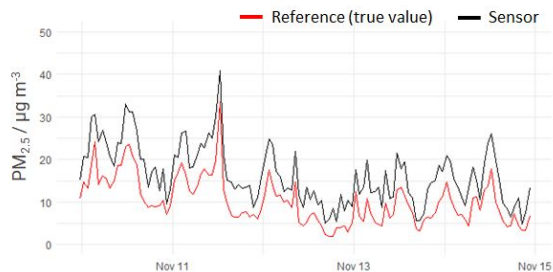


MAE = 10.4  $\mu\text{g/m}^3$  RMSE = 12.0  $\mu\text{g/m}^3$

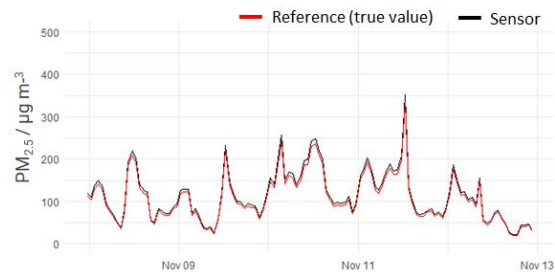
The higher the error of the sensor (MAE / RMSE), the lower the accuracy.

# Example II: Polluted vs. “Clean”

## Less polluted



## More polluted



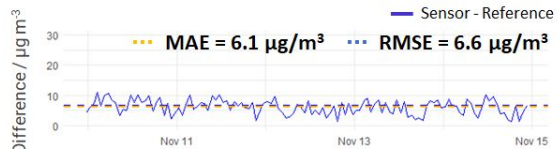
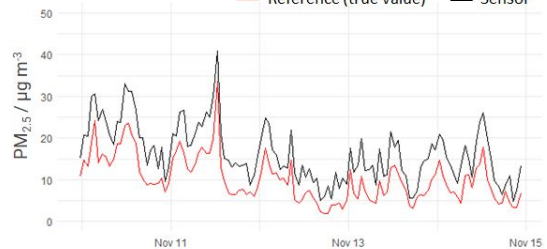


# Example II: Polluted vs. "Clean"

## Less polluted



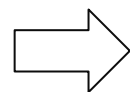
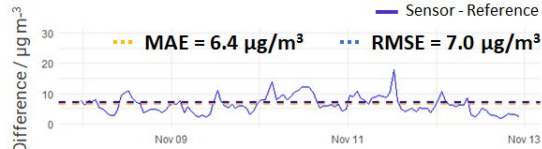
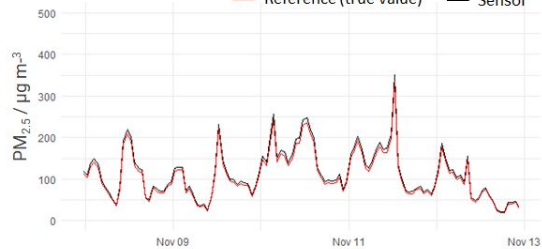
— Reference (true value) — Sensor



## More polluted



— Reference (true value) — Sensor



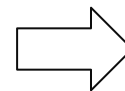
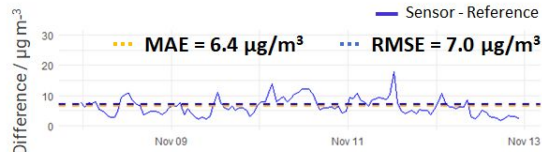
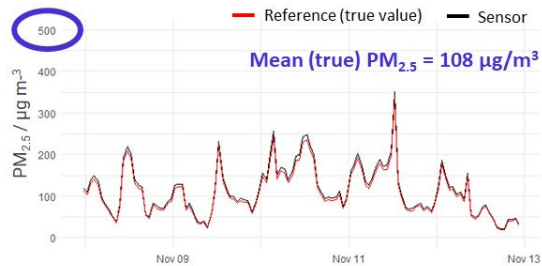
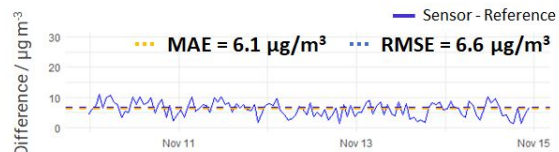
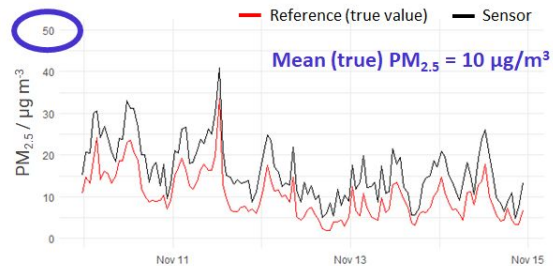
Same error = same performance?

# Example II: Polluted vs. “Clean”

## Less polluted



## More polluted



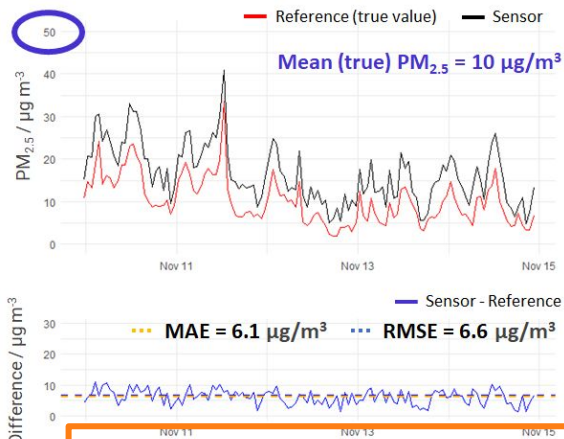
Error has relatively high impact in cleaner environment

# Example II: Polluted vs. "Clean"

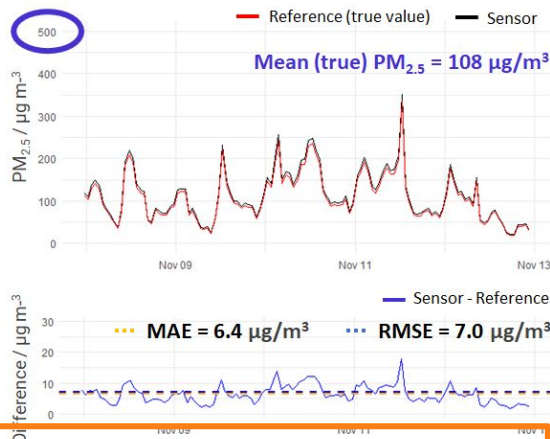
## Less polluted



## More polluted



$$nRMSE = 6.6 \mu g m^{-3} / 10 \mu g m^{-3} = 66 \%$$

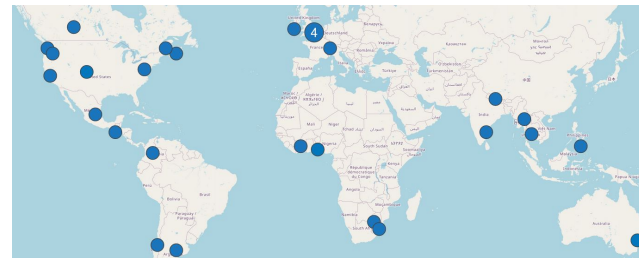


$$nRMSE = 7.0 \mu g m^{-3} / 108 \mu g m^{-3} = 6.5 \%$$

## Normalised RMSE

= RMSE / average concentration

→ helps to compare sensors across different environments





How far is a sensor from true value?

Determined via co-location with reference.



Quantification via the mean error (MAE / RMSE).

Normalise to compare across different locations.



# How to measure the **precision** of a sensor?



High accuracy  
Low precision

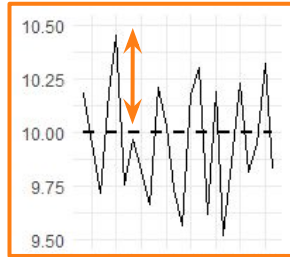


High accuracy  
High precision

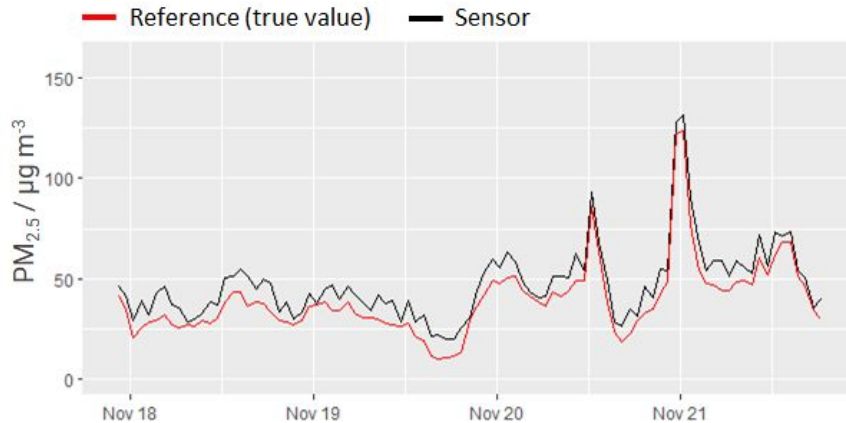
# How to measure the precision of a sensor?

## Precision:

Distance of the measurements from the average value



*Repeated measurements  
@ stable concentration*



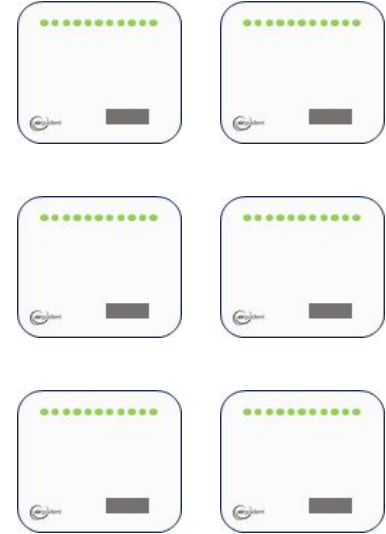
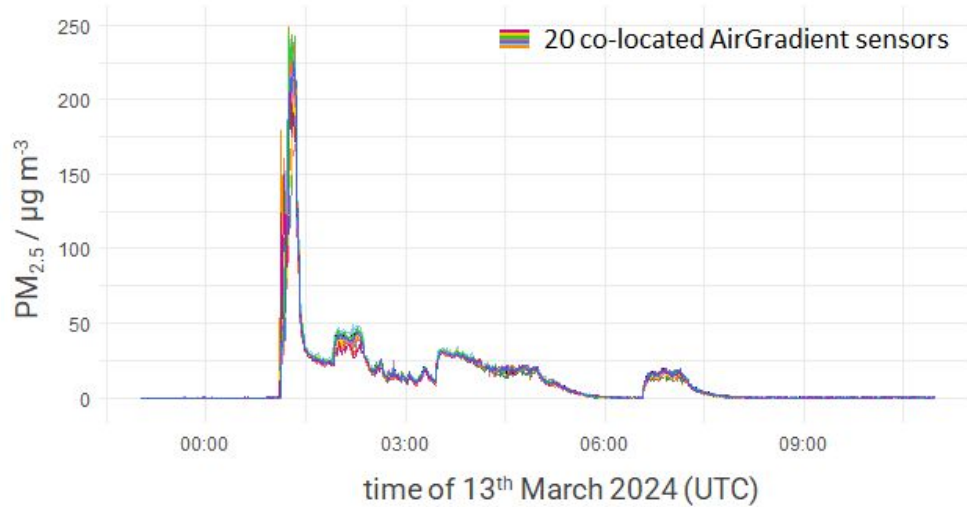
*No stable concentration!*



# How to measure the ~~precision~~ reproducibility of a sensor?

## Reproducibility:

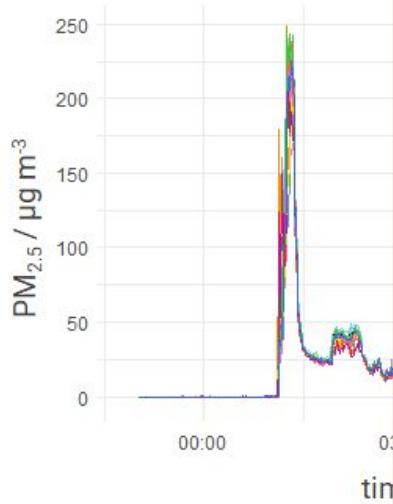
The consistency of measurements obtained from multiple sensors placed in the same location



# How to measure the ~~precision~~ reproducibility of a sensor?

## Reproducibility:

The consistency of measurements obtained from multiple sensors placed in the same location

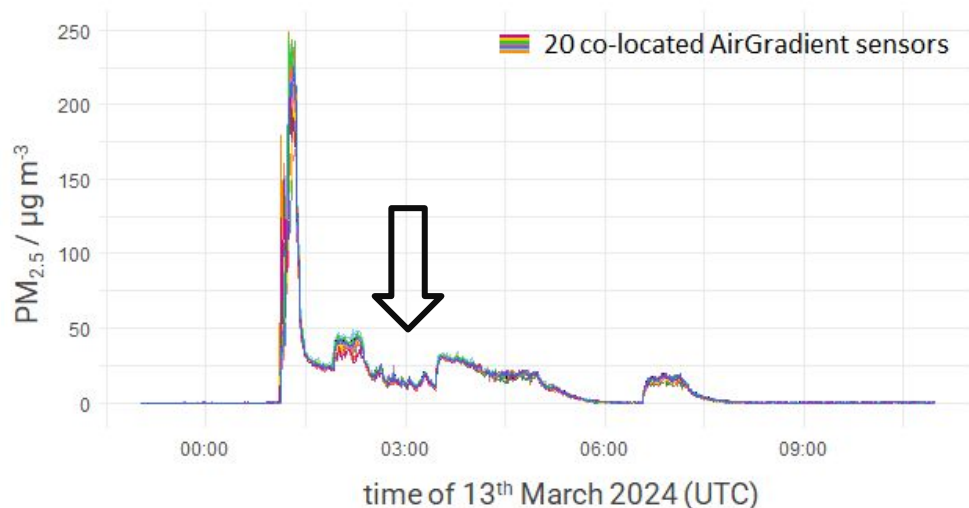




# How to measure the ~~precision~~ reproducibility of a sensor?

## Reproducibility:

The consistency of measurements obtained from multiple sensors placed in the same location



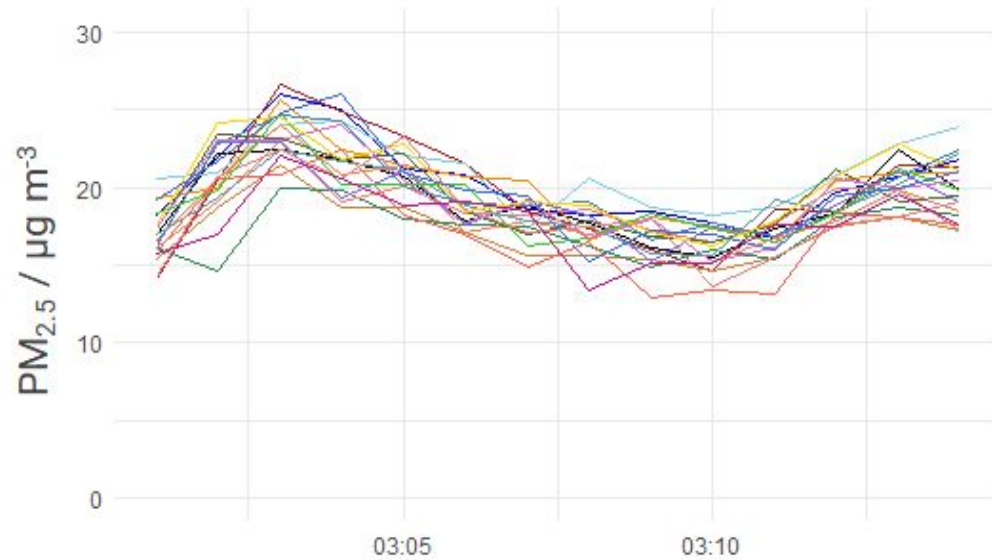
## Precision:

Spread of a sensor's measurements around a constant value.

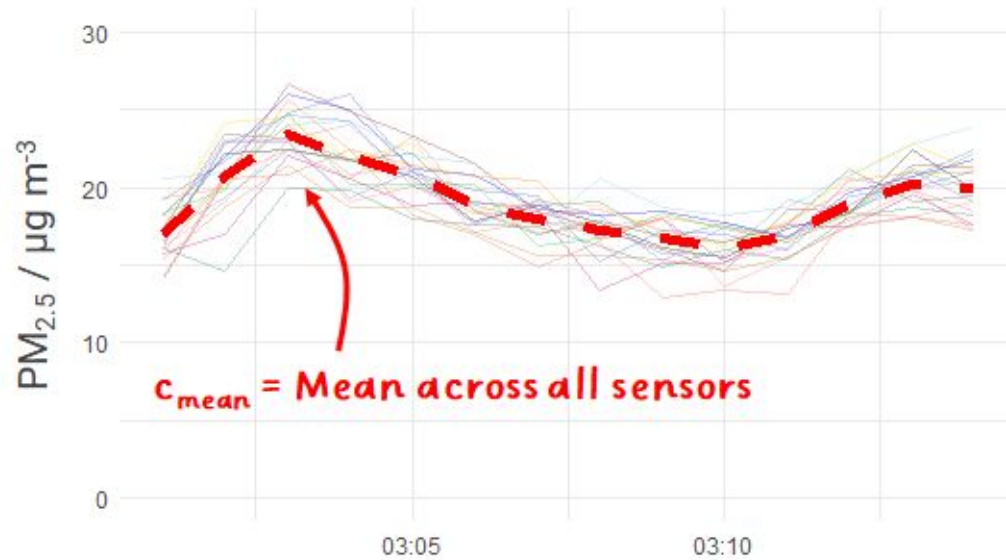


Spread of multiple sensors around their average value

# How to measure the reproducibility of a sensor?

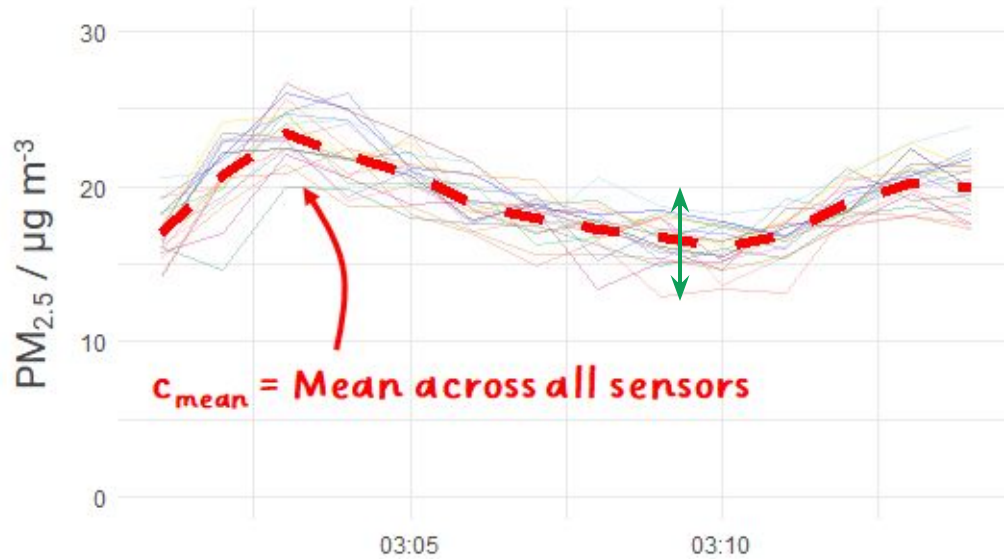


# How to measure the reproducibility of a sensor?



$$c_{mean} = \frac{1}{x} \sum_x c_{sensor\ x}$$

# How to measure the reproducibility of a sensor?



The narrower the spread around the mean, the bigger the reproducibility.

$$c_{mean} = \frac{1}{x} \sum_x c_{sensor\ x}$$

# Reproducibility = Precision + Consistency

## Precision

“Stability” of measurements over time;  
Absence of noise.



## Consistency:

Different sensors measure the same values.

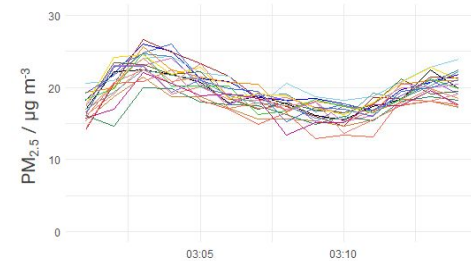
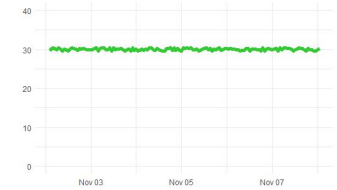
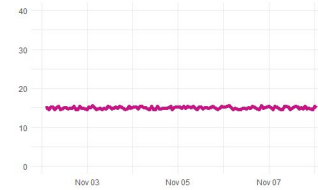
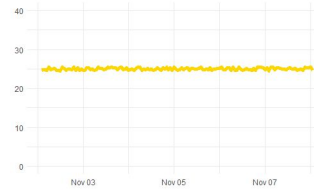
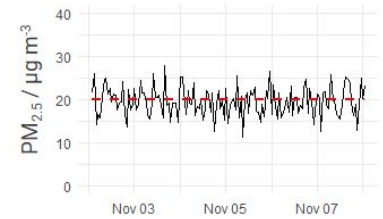
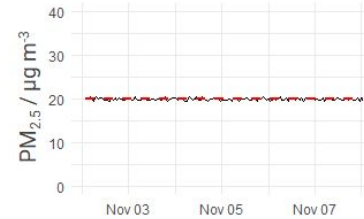


## Reproducibility:

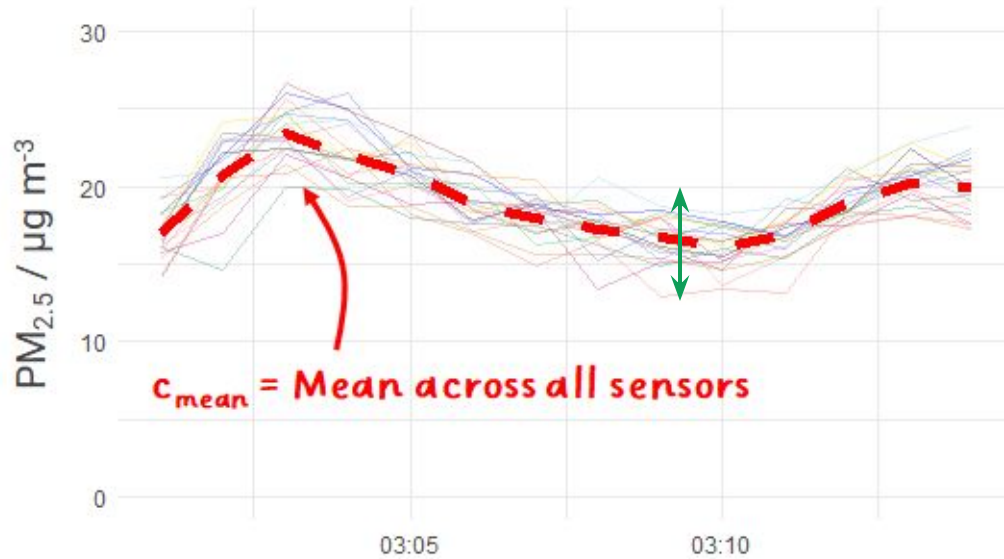
Co-located sensors measure the same.

→ **Requires precision and consistency.**

(Hence, the EPA refers to it as precision.)



# How to measure the reproducibility of a sensor?



$$c_{mean} = \frac{1}{x} \sum_x c_{sensor\ x}$$

The narrower the spread around the mean, the bigger the reproducibility.

## Standard Deviation (SD)

= Measure for width of spread

“Error across sensors”

# How to measure the reproducibility of a sensor?

## Standard Deviation

Standard Deviation  
of the sensor  $x$

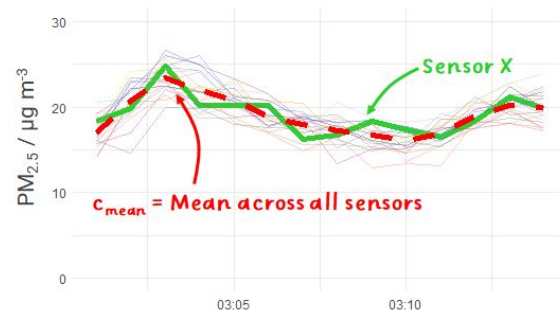
Root to compensate  
for the squaring

Squaring makes  
everything positive

$$\text{SD}(\text{sensor}_x) = \sqrt{\frac{1}{n} \sum_n (c_{\text{sensor}_x, n} - c_{\text{mean}, n})^2}$$

Taking the mean

Difference between sensor  $x$   
and the average

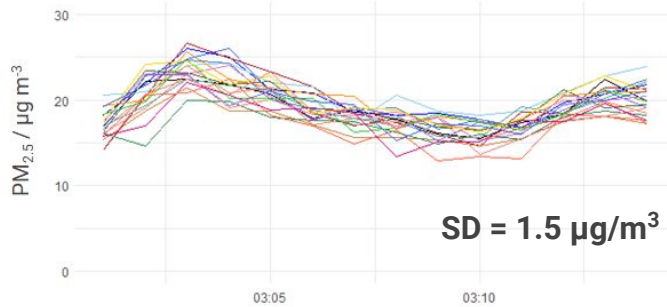


**The lower the SD,  
the higher the  
precision.**

*Math “fun fact”: The calculation is the same as for the RMSE, but you use the mean concentration instead of the reference concentration.*

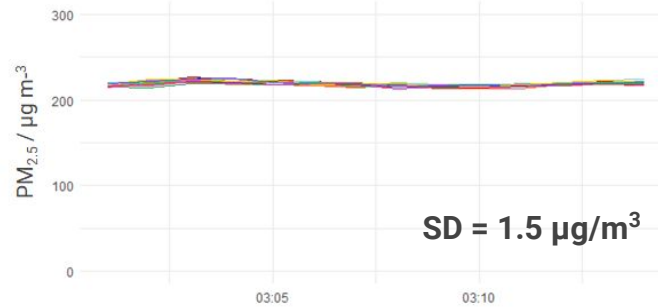
# Polluted vs. “clean”

## Less polluted



$$CV = 1.5 \mu\text{g}/\text{m}^3 / 19 \mu\text{g}/\text{m}^3 = 7.9\%$$

## More polluted



$$CV = 1.5 \mu\text{g}/\text{m}^3 / 219 \mu\text{g}/\text{m}^3 = 0.7\%$$

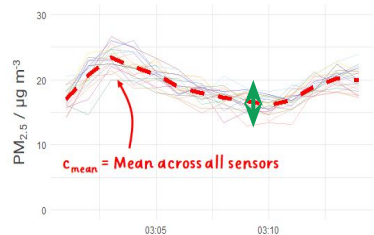
## Normalised SD

= SD / average concentration

= “Coefficient of variation” (CV)



# Recap precision



What's the spread of the measurements

Determined via co-location of multiple sensors




Quantification via Standard Deviation



Normalise to compare across different locations




# What's an acceptable error?

 EPA  
United States  
Environmental Protection  
Agency

EPA/600/R-20/280 | February 2021

## Performance Testing Protocols, Metrics, and Target Values for Fine Particulate Matter Air Sensors

USE IN AMBIENT, OUTDOOR, FIXED SITE, NON-REGULATORY SUPPLEMENTAL AND INFORMATIONAL MONITORING APPLICATIONS



Office of Research and Development  
Center for Environmental Measurement and Modeling

## EPA target values

Precision	Standard Deviation (SD)	$\leq 5 \mu\text{g}/\text{m}^3$
	-OR- Coefficient of Variation (CV)	$\leq 30\%$
Error	Root Mean Square Error (RMSE) or Normalized Root Mean Square Error (NRMSE)	$\text{RMSE} \leq 7 \mu\text{g}/\text{m}^3$ or $\text{NRMSE} \leq 30\%^\dagger$

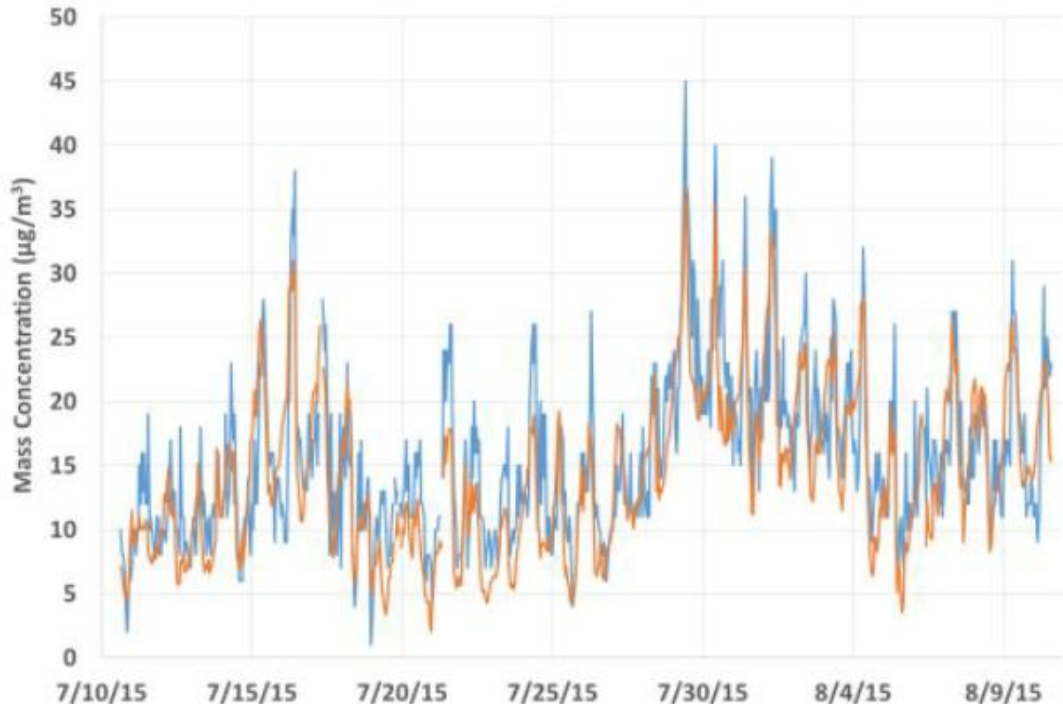
From Table 4-2: Recommended Performance Metrics and Target Values for PM2.5 Air Sensors Used in Ambient, Outdoor, Fixed Site, NSIM Applications. All values for 24h averaged data.

## Further aspects of sensing performance: Linearity ( $R^2$ ), Bias (Slope, intercept)

# Is an 30% error to much?

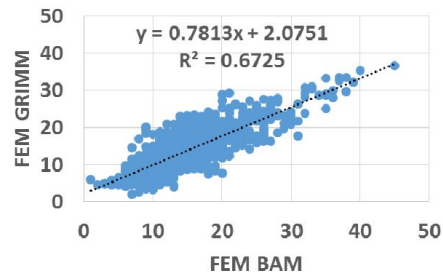
FEM BAM vs FEM GRIMM (PM<sub>2.5</sub>; 1-hr mean)

— FEM BAM — FEM GRIMM



FEM - Federal Equivalent Method

PM<sub>2.5</sub> (1-hr Mean; µg/m<sup>3</sup>)



## Comparison of two reference instruments.

AQ-SPEC; South Coast Air Quality Management District, USA

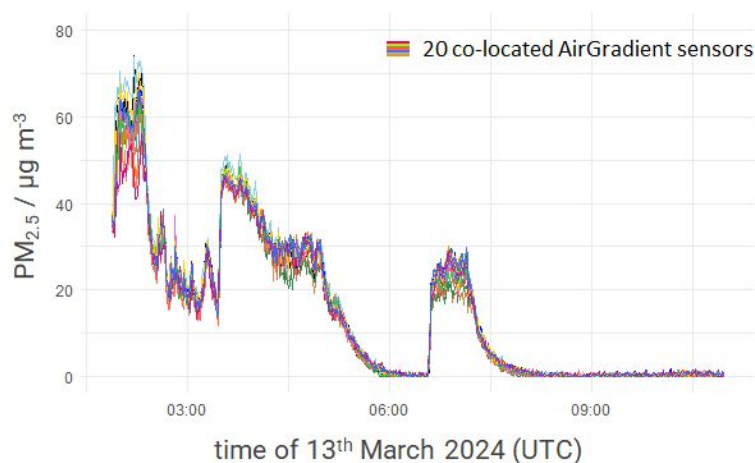
→ They can differ a lot!

Let's dive into that later...

# Real world examples of sensor performance assessment



## Precision of AirGradient indoor monitors in testing chamber



**SD** across all sensors:  $\pm 1.6 \mu\text{g/m}^3$

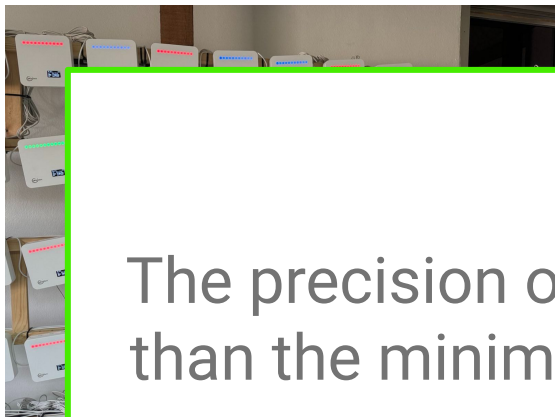
Average concentration of test run:  $14.8 \mu\text{g/m}^3$

**CV** =  $1.6 \mu\text{g/m}^3 / 14.8 \mu\text{g/m}^3 = \pm 10.8\%$

**< 5  $\mu\text{g/m}^3$  → within EPA guidelines**

**< 30% → within EPA guidelines**

## Precision of AirGradient indoor monitors in testing chamber



### Conclusion

The precision of AirGradient PM<sub>2.5</sub> sensors is higher than the minimum precision recommended by EPA.

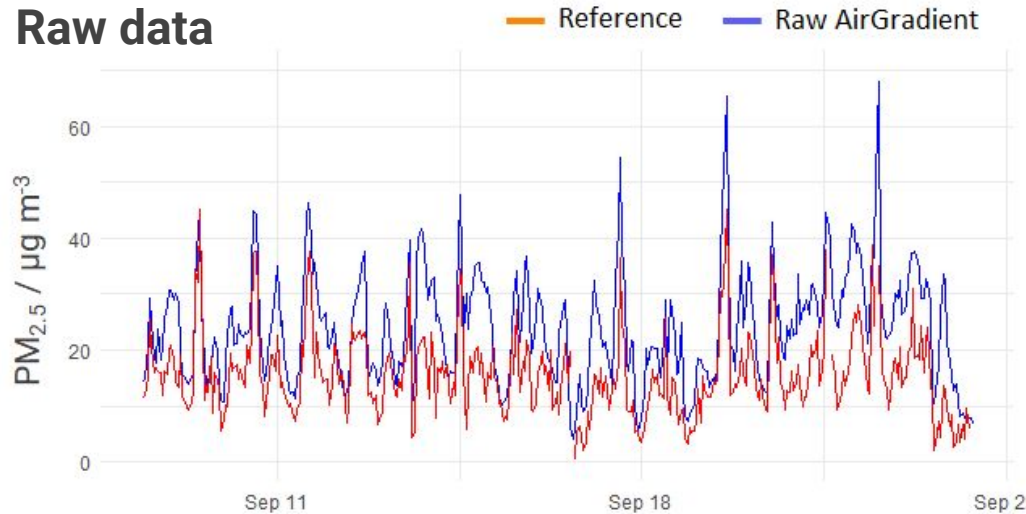
SD across

Average concentration of test run: 14.8  $\mu\text{g}/\text{m}^3$

CV =  $1.6 \mu\text{g}/\text{m}^3 / 14.8 \mu\text{g}/\text{m}^3 = \pm 10.8\%$  < 30% → within EPA guidelines

## Accuracy of AirGradient outdoor monitor in Chennai

### Raw data



**RMSE =  $\pm 10.0 \mu\text{g/m}^3$**

Average concentration of test run:  $15.6 \mu\text{g/m}^3$

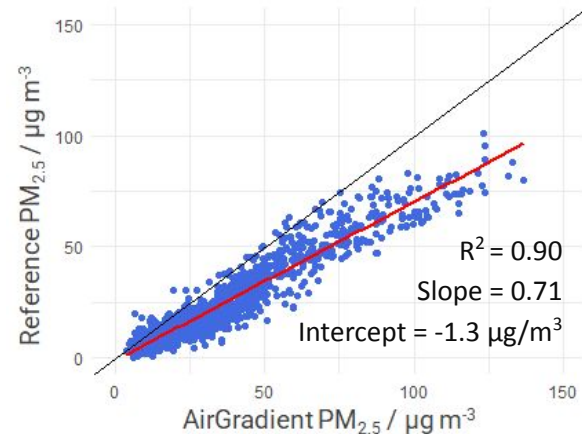
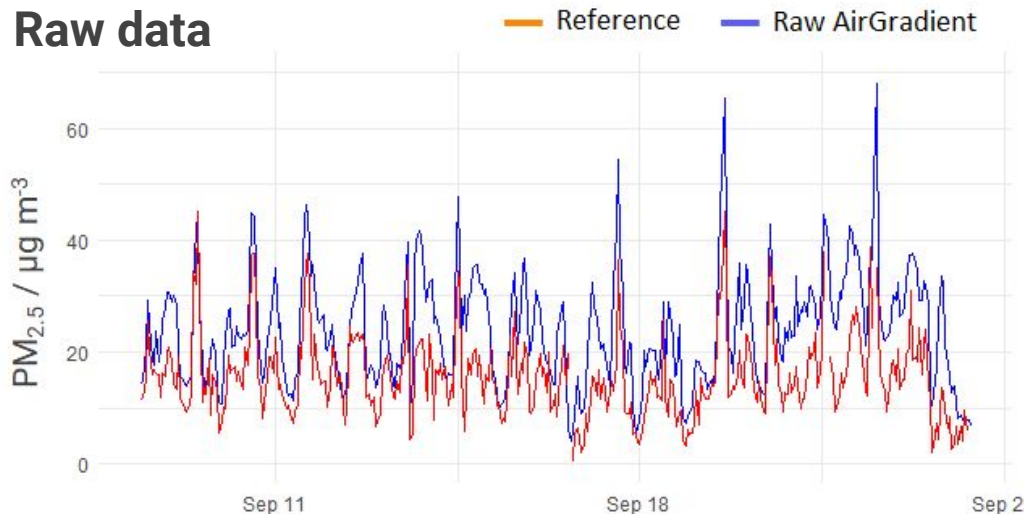
**nRMSE =  $10.0 \mu\text{g/m}^3 / 15.6 \mu\text{g/m}^3 = \pm 64.5\%$**

**$> 7 \mu\text{g/m}^3 \rightarrow$  not within EPA guidelines**

**$> 30\% \rightarrow$  not within EPA guidelines**

## Accuracy of AirGradient outdoor monitor in Chennai

### Raw data



**RMSE =  $\pm 10.0 \mu\text{g m}^{-3}$**

Average concentration of test run:  $15.6 \mu\text{g m}^{-3}$

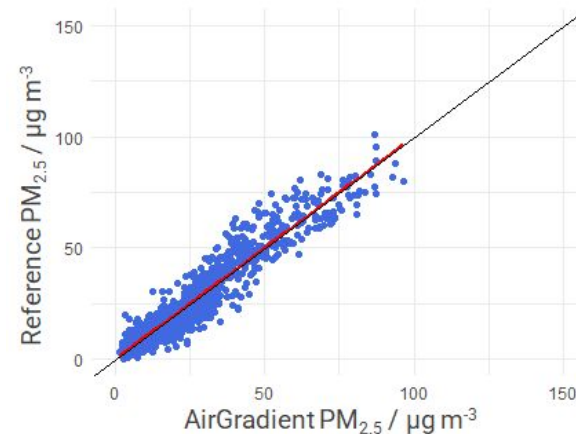
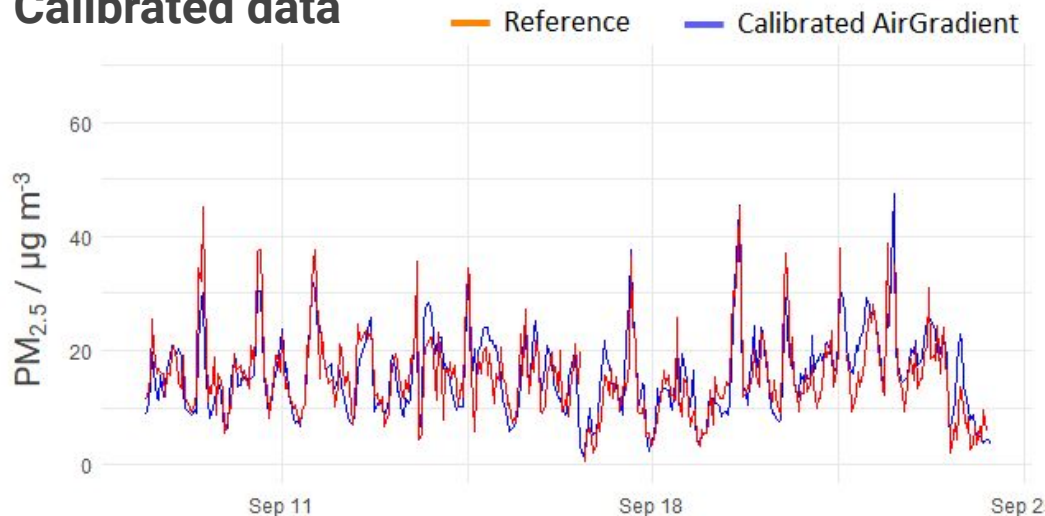
**nRMSE =  $10.0 \mu\text{g m}^{-3} / 15.6 \mu\text{g m}^{-3} = \pm 64.5\%$**

More information about linearity and sensor calibration:  
[https://youtu.be/b5mSJSS9i\\_A?feature=shared](https://youtu.be/b5mSJSS9i_A?feature=shared)  
<https://youtu.be/CXueV0Am80Y?feature=shared>



## Accuracy of **calibrated** AirGradient outdoor monitors in Chennai

### Calibrated data



**RMSE =  $\pm 4.4 \mu\text{g/m}^3$**

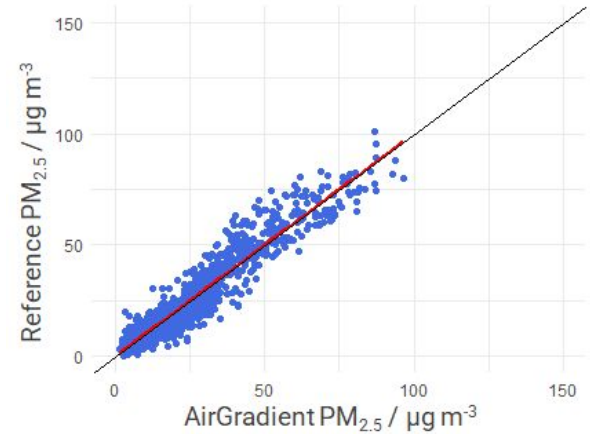
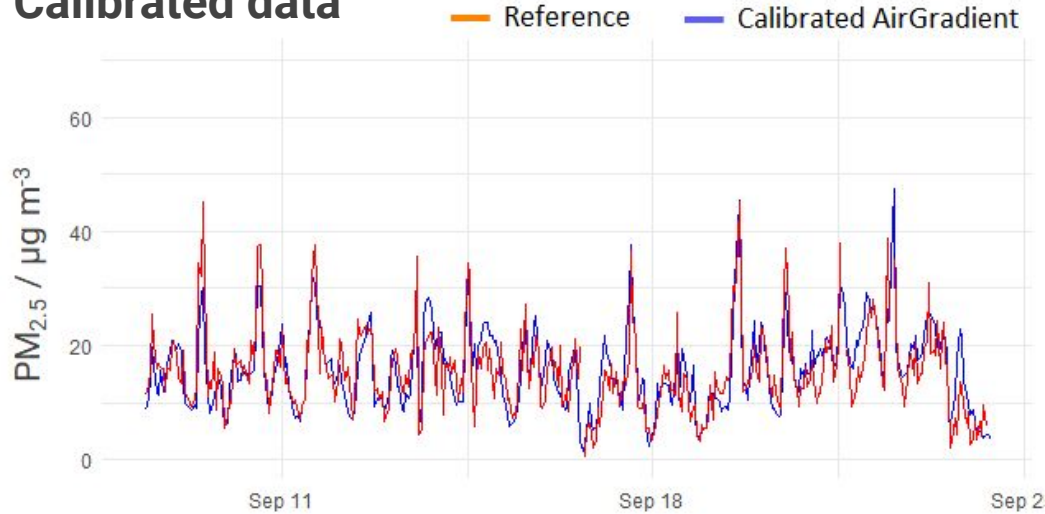
Average concentration of test run:  $15.6 \mu\text{g/m}^3$

**nRMSE =  $4.4 \mu\text{g/m}^3 / 15.6 \mu\text{g/m}^3 = \pm 28.2 \%$**

More information about linearity and sensor calibration:  
[https://youtu.be/b5mSJSS9i\\_A?feature=shared](https://youtu.be/b5mSJSS9i_A?feature=shared)  
<https://youtu.be/CXueV0Am80Y?feature=shared>

## Accuracy of **calibrated** AirGradient outdoor monitors in Chennai

### Calibrated data



**RMSE =  $\pm 4.4 \mu\text{g/m}^3$**

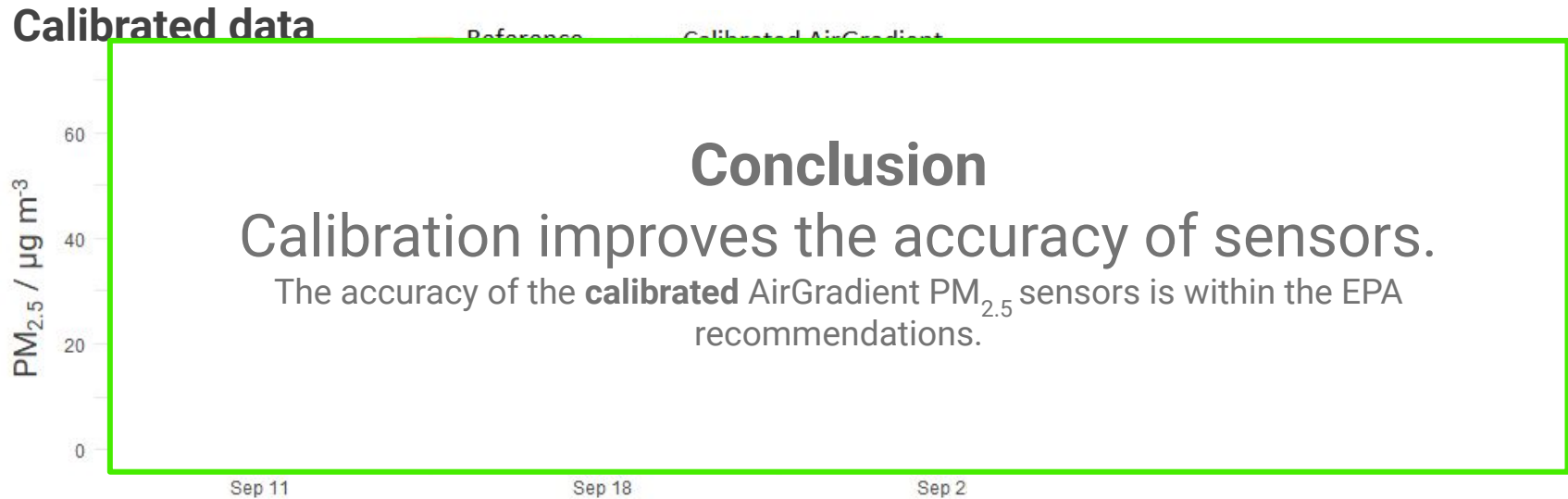
Average concentration of test run:  $15.6 \mu\text{g/m}^3$

**nRMSE =  $4.4 \mu\text{g/m}^3 / 15.6 \mu\text{g/m}^3 = \pm 28.2 \%$**

**$< 7 \mu\text{g/m}^3 \rightarrow$  within EPA guidelines**

**$< 30\% \rightarrow$  within EPA guidelines**

## Accuracy of **calibrated** AirGradient outdoor monitors in Chennai



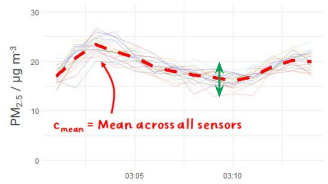
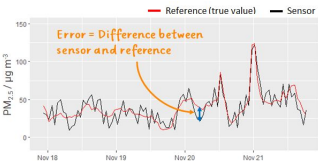
**RMSE = ± 4.4 µg/m<sup>3</sup>**

Average concentration of test run: 15.6 µg/m<sup>3</sup>

**nRMSE = 4.4 µg/m<sup>3</sup> / 15.6 µg/m<sup>3</sup> = ± 28.2 %**

**< 7 µg/m<sup>3</sup> → within EPA guidelines**

**< 30% → within EPA guidelines**

	Definition	Experiment	Performance parameter	EPA recommendation	Improve via
<h2>Precision</h2>  <p>PM<sub>2.5</sub> / <math>\mu\text{g m}^{-3}</math></p> <p><math>c_{\text{mean}}</math> = Mean across all sensors</p>	Consistency of measurements.	Sensor - sensor co-location	SD, CV	$\leq 5 \mu\text{g/m}^3$ , $\leq 30\%$	Averaging
<h2>Accuracy</h2>  <p>— Reference (true value) — Sensor</p> <p>Error = Difference between sensor and reference</p> <p>PM<sub>2.5</sub> / <math>\mu\text{g m}^{-3}</math></p>	Agreement of measurement with true value.	Reference - sensor co-location	RMSE, nRMSE, MAE	$\leq 7 \mu\text{g/m}^3$ , $\leq 30\%$	Calibration

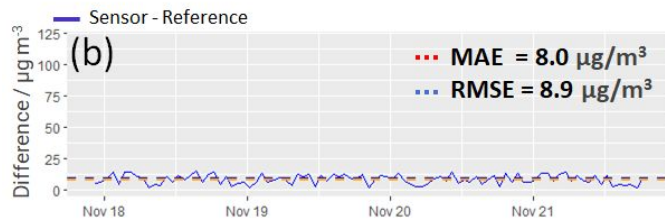
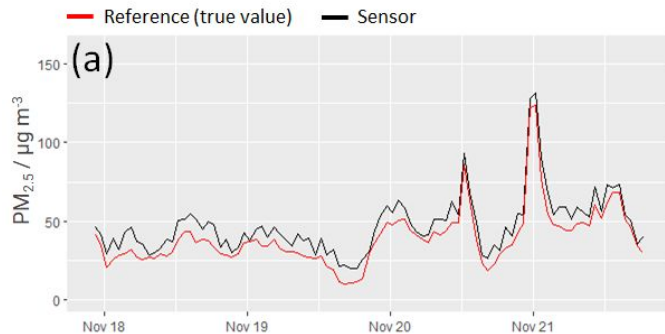
# Questions?



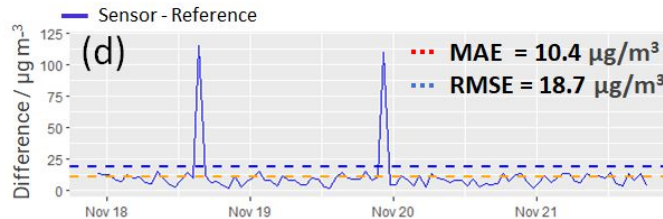
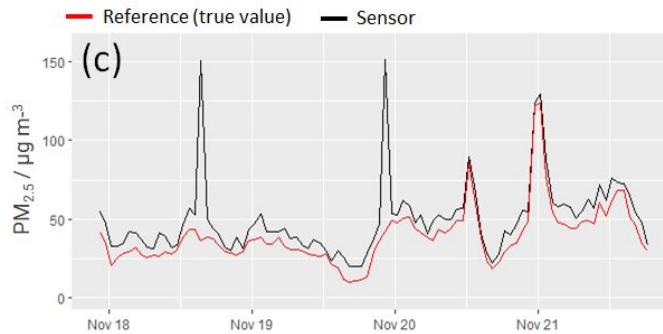
# Appendix

# Mean Absolute Error vs. Root Mean Square Error

## RMSE $\approx$ MAE (no outliers)



## RMSE $>$ MAE (outliers)



Larger difference  
between RMSE and  
MAE when outliers  
occur.